

In[1]:= Needs ["SpinDynamica`"]

SpinDynamica version 3.0.1 loaded

... **ModifyBuiltin**: The following built-in routines have been modified in SpinDynamica:
{Chop, Dot, Duration, Exp, Expand, ExpandAll, NumericQ, Plus, Power, Simplify, Times, WignerD}.
Evaluate ??symbol to generate the additional definitions for symbol.

In[2]:= SetSpinSystem[3]

... **SetSpinSystem**: the spin system has been set to $\{\{1, \frac{1}{2}\}, \{2, \frac{1}{2}\}, \{3, \frac{1}{2}\}\}$

... **SetBasis**: the state basis has been set to ZeemanBasis $\{\{\{1, \frac{1}{2}\}, \{2, \frac{1}{2}\}, \{3, \frac{1}{2}\}\}, \text{BasisLabels} \rightarrow \text{Automatic}\}$.

In[3]:= ExpressOperator[opI[1, "x"].opI[2, "+"].opI[3, "z"],
CartesianProductOperatorBasis[]
]

Out[3]= $I_{1x} \cdot I_{2x} \cdot I_{3z} + i (I_{1x} \cdot I_{2y} \cdot I_{3z})$

In[4]:= ExpressOperator[opI[1, "x"].opI[2, "+"].opI[3, "z"],
ShiftAndPolarizationOperatorBasis[]
]

Out[4]= $\frac{1}{4} (I_1^- \cdot I_2^+ \cdot I_3^\alpha) - \frac{1}{4} (I_1^- \cdot I_2^+ \cdot I_3^\beta) + \frac{1}{4} (I_1^+ \cdot I_2^- \cdot I_3^\alpha) - \frac{1}{4} (I_1^+ \cdot I_2^- \cdot I_3^\beta)$

In[5]:= ExpressOperator[opI[1, "x"].opI[2, "+"].opI[3, "z"],
ShiftAndZOperatorBasis[]
]

Out[5]= $\frac{1}{2} (I_1^- \cdot I_2^+ \cdot I_{3z}) + \frac{1}{2} (I_1^+ \cdot I_2^- \cdot I_{3z})$

In[6]:= ExpressOperator[
ProjectionOperator[Ket[" $\alpha\beta\alpha$ "]],
CartesianProductOperatorBasis[]
]

Out[6]= $-\frac{1}{2} (I_{1z} \cdot I_{2z}) + \frac{1}{2} (I_{1z} \cdot I_{3z}) - \frac{1}{2} (I_{2z} \cdot I_{3z}) - I_{1z} \cdot I_{2z} \cdot I_{3z} + \frac{I_{1z}}{4} - \frac{I_{2z}}{4} + \frac{I_{3z}}{4} + \frac{1}{8}$

In[7]:= ExpressOperator[
ShiftOperator[Ket[" $\alpha\beta\alpha$ "], Bra[" $\alpha\alpha\beta$ "]],
CartesianProductOperatorBasis[]
]

Out[7]= $\frac{1}{2} (I_{2x} \cdot I_{3x}) + \frac{1}{2} i (I_{2x} \cdot I_{3y}) - \frac{1}{2} i (I_{2y} \cdot I_{3x}) + \frac{1}{2} (I_{2y} \cdot I_{3y}) +$
 $I_{1z} \cdot I_{2x} \cdot I_{3x} + i (I_{1z} \cdot I_{2x} \cdot I_{3y}) - i (I_{1z} \cdot I_{2y} \cdot I_{3x}) + I_{1z} \cdot I_{2y} \cdot I_{3y}$

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In[8]:= ExpressOperator[
  ShiftOperator[Ket["αβα"], Bra["ααβ"]],
  SphericalTensorOperatorBasis[]
]
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$$\begin{aligned}
\text{Out[8]} = & \frac{1}{4} (\mathbf{I}_2 \cdot \mathbf{I}_3^+ - \mathbf{I}_2^+ \cdot \mathbf{I}_3^-) + \frac{1}{12} (\mathbf{I}_2 \cdot \mathbf{I}_3^+ + \mathbf{I}_2^+ \cdot \mathbf{I}_3^- - 4 (\mathbf{I}_{2z} \cdot \mathbf{I}_{3z})) + \\
& \frac{1}{6} (\mathbf{I}_2 \cdot \mathbf{I}_3^+ + \mathbf{I}_2^+ \cdot \mathbf{I}_3^- + 2 (\mathbf{I}_{2z} \cdot \mathbf{I}_{3z})) + \frac{1}{4} (\mathbf{I}_1^- \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^+ - \mathbf{I}_1^+ \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^- + \mathbf{I}_{1z} \cdot \mathbf{I}_2^- \cdot \mathbf{I}_3^+ - \mathbf{I}_{1z} \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_3^-) + \\
& \frac{1}{6} (\mathbf{I}_1^- \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_{3z} - \mathbf{I}_1^- \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^+ - \mathbf{I}_1^+ \cdot \mathbf{I}_2^- \cdot \mathbf{I}_{3z} + \mathbf{I}_1^+ \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^- + \mathbf{I}_{1z} \cdot \mathbf{I}_2^- \cdot \mathbf{I}_3^+ - \mathbf{I}_{1z} \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_3^-) + \\
& \frac{1}{12} (-2 (\mathbf{I}_1^- \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_{3z}) - \mathbf{I}_1^- \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^+ + 2 (\mathbf{I}_1^+ \cdot \mathbf{I}_2^- \cdot \mathbf{I}_{3z}) + \mathbf{I}_1^+ \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^- + \mathbf{I}_{1z} \cdot \mathbf{I}_2^- \cdot \mathbf{I}_3^+ - \mathbf{I}_{1z} \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_3^-) + \\
& \frac{1}{4} (- (\mathbf{I}_1^- \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^+) - \mathbf{I}_1^+ \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^- + \mathbf{I}_{1z} \cdot \mathbf{I}_2^- \cdot \mathbf{I}_3^+ + \mathbf{I}_{1z} \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_3^-) + \\
& \frac{1}{10} (\mathbf{I}_1^- \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_{3z} + \mathbf{I}_1^- \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^+ + \mathbf{I}_1^+ \cdot \mathbf{I}_2^- \cdot \mathbf{I}_{3z} + \mathbf{I}_1^+ \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^- + \mathbf{I}_{1z} \cdot \mathbf{I}_2^- \cdot \mathbf{I}_3^+ + \mathbf{I}_{1z} \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_3^- - 4 (\mathbf{I}_{1z} \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_{3z})) + \\
& \frac{1}{20} (-2 (\mathbf{I}_1^- \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_{3z}) + 3 (\mathbf{I}_1^- \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^+) - 2 (\mathbf{I}_1^+ \cdot \mathbf{I}_2^- \cdot \mathbf{I}_{3z}) + \\
& 3 (\mathbf{I}_1^+ \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_3^-) + 3 (\mathbf{I}_{1z} \cdot \mathbf{I}_2^- \cdot \mathbf{I}_3^+) + 3 (\mathbf{I}_{1z} \cdot \mathbf{I}_2^+ \cdot \mathbf{I}_3^-) + 8 (\mathbf{I}_{1z} \cdot \mathbf{I}_{2z} \cdot \mathbf{I}_{3z}))
\end{aligned}$$